## FedDIP: Federated Learning with Extreme Dynamic Pruning and Incremental Regularization

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#### ► Introduction

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- ▶ Theoretical & Experimental Results
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# Applications & Challenges



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#### Applications

- Healthcare
- Mobile Devices
- Autonomous Vehicles



#### Challenges

- Computation
- Communication
- Model Inference

Efficient Federated Learning with **Compression**!

# SOTAs' Limitations & Our Contribution

#### Introduction



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#### (SOTAs) Categorized by model training

- Dense to Dense: Only gradients
- Dense to Sparse: Excessive memory
- Sparse to Sparse: Insufficient sparsity level

#### Highlights

- Dynamic pruning with error feedback and regularization in FL
- Sparse to Extreme Sparse  $(s_p > 0.8$  for i.i.d and non-i.i.d)
- Convergence analysis with theoretical support

#### Model Pruning

Before Pruning



After Pruning





### **DPF & Incremental Regularization**

Methodology 2



Dynamic Pruning with error Feedback  $(\mathbf{DPF}^{a})$ :

$$\boldsymbol{\omega}_{t+1} = \boldsymbol{\omega}_t - \eta_t \nabla f(\boldsymbol{\omega}_t \odot \mathbf{m}_t)$$
(1)

$$= \boldsymbol{\omega}_t - \eta_t \nabla f(\boldsymbol{\omega}_t + \mathbf{e}_t) \tag{2}$$



$$\lambda_t = \begin{cases} 0 & \text{if } 0 \le t < \frac{T}{Q} \\ \vdots & \vdots \\ \frac{\lambda_{\max}(Q-1)}{Q} & \text{if } \frac{(Q-1)T}{Q} \le t \le T \end{cases}$$
(3)

<sup>a</sup>Tao Lin et al. (2019). "Dynamic Model Pruning with Feedback". In: International Conference on Learning Representations (ICLR).

<sup>b</sup>Huan Wang et al. (2021). "Neural Pruning via Growing Regularization". In: International Conference on Learning Representations (ICLR).



### FedDIP Diagram

Methodology 2



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#### **Benefits:**

- DPF in FL:
  - -- Reduce downloading cost
  - Avoid long time post-pruning fine-tune
  - Suitable for high sparsity pruning

- IR with DPF:
  - Consistent weight importance scoring
  - Hessian Information for accurate pruning







#### Theorem (FedDIP Convergence)

Consider the general assumption, and let  $\eta_t = \frac{1}{tL}$ , L > 0. Then, the convergence rate of the FedDIP process is bounded by:

$$\frac{1}{T} \sum_{t=1}^{T} \|\nabla f(\bar{\omega}^{\prime(t)})\|^2 \leq 2L\mathbb{E}(f(\omega_1) - f^*) + \frac{2L\sum_{t=1}^{T} [\mu \mathbb{E}[\sqrt{\delta_{t+1}} \|\bar{\omega}^{t+1}\|]]}{3L^2} + \frac{\pi^2}{3L^2} \chi, \quad (4)$$

where  $f(\boldsymbol{\omega}_1)$  and  $f^*$  stand for the initial loss and the final convergent stable loss, with  $\chi = \frac{(\gamma-1)L^2+L}{2K}\sum_{n=1}^N \rho_n \sigma_n^2 + \frac{(\gamma-1)\gamma E_l^2 L^2 G^2}{2}$ , and  $\gamma$  is the data dispersion degree.

## **Experimental Results**

Theoretical & Experimental Results 3



**Datasets & Models:** Evaluate *LeNet-5* ( $s_p = 0.9$ ) on Fashion-MNIST, *AlexNet* ( $s_p = 0.9$ ) on CIFAR10, and *ResNet-18* ( $s_p = 0.8$ ) on CIFAR100.







Figure: AlexNet: Accuracy vs Training Rounds



Figure: ResNet-18: Accuracy vs Training Rounds

### **Experimental Results**

Theoretical & Experimental Results 3





Figure: Performance under Extreme Sparsities



Figure: Sparsity Distribution of ResNet18







Impact: Because of extreme pruning in FL, FedDIP contributes as follows.

- Faster Training
- Less Memory Required
- Less Downloading Cost

#### Future Work

- Mask Personalization
- Decentralized FL









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Thank you!